KEY

Math 300: Quiz the First

9.11.08

This exam is closed book and closed notes. You may not use a calculator. You have until 5 minutes before the hour to finish the in-class portion. The take-home portion is due Tuesday at the beginning of class.

- 1. True or False. Give a brief justification in each case.
 - (a) If a system of equations has at least two solutions, then it has infinitely many solutions.

True Systems have O, I, or inf. many solutions

(b) In performing a row-reduction, you may multiply a row by any scalar.

False. Scalar most be nonzero

(c) A matrix might have more than one row-reduced echelon form.

False. The RREF is unique

(d) The zero vector is in the span of any set of vectors.

True 0=00,+00,1-+00p

(e) For every vector \mathbf{x} in \mathbb{R}^m , there is a vector \mathbf{y} in \mathbb{R}^m such that $\mathbf{x} + \mathbf{y} = \mathbf{0}$.

True $\chi = \begin{bmatrix} \chi_1 \\ \chi_2 \\ \vdots \\ \chi_m \end{bmatrix}$ $y = \begin{bmatrix} -\chi_1 \\ -\chi_2 \\ -\chi_m \end{bmatrix}$

2. Solve the following system of equations:

$$x_1 - x_2 - x_3 = 6 (1)$$

$$2x_1 + x_2 - 3x_3 = 2 (2)$$

$$x_1 - 4x_3 = 0 (3)$$

$$\begin{bmatrix} 1 & -1 & -1 & 6 \\ 2 & 1 & -3 & 2 \\ 1 & 0 & -4 & 0 \end{bmatrix} \xrightarrow{R_{2} - 2R_{1}} \begin{bmatrix} 0 & 3 & -1 & -10 \\ 0 & 3 & -1 & -10 \\ 0 & 1 & -3 & -6 \end{bmatrix} \xrightarrow{R_{3} - 2R_{1}} \begin{bmatrix} 0 & 1 & -3 & -6 \\ 0 & 1 & -3 & -6 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$R_{3} - 3R_{2} \begin{bmatrix} 0 & 1 & -1 & 6 \\ 0 & 1 & -3 & -6 \\ 0 & 0 & 1 & 1 \end{bmatrix} \xrightarrow{R_{3} - 3R_{2}} \begin{bmatrix} 1 & -1 & 0 & 7 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 1 \end{bmatrix} \xrightarrow{R_{3} - 3R_{2}} \begin{bmatrix} 1 & 0 & 0 & 1 & 4 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 1 \end{bmatrix} \xrightarrow{R_{3} - 3R_{2}} \begin{bmatrix} 1 & 0 & 0 & 1 & 4 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$\chi_{1} = 4 \quad \chi_{2} = -3, \quad \chi_{3} = 1$$

3. Write
$$\begin{bmatrix} 6 \\ 2 \\ 0 \end{bmatrix}$$
 as a linear combination of $\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, $\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$, and $\begin{bmatrix} -1 \\ -3 \\ -4 \end{bmatrix}$

from above
$$\begin{bmatrix} 6 \\ 2 \\ 0 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + (-3) \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} -1 \\ -3 \\ -4 \end{bmatrix}$$

4. (a) Suppose that you have a system of equations with more equations than unknowns. Might it have zero, one, or infinitely many solutions? Explain for all that apply.

More equations thoman knows overdetermined but might have

$X_1 + X_2 = 2$	$x_1 + x_2 = 2$	$X_{i} + X_{i} = 2$
$X_1 + 2x_2 = 3$	$x_1 + x_2 = 3$	$2x_{i} + 2x_{2} = 4$
$2x_2 + 3x_3 = 4$	$2x_2 + 3x_3 = 5$	$3x_{i} + 3x_{2} = 6$
0		00 many

(b) Suppose that you have a system of equations with as many equations as unknowns. Might it have zero, one, or infinitely many solutions? Explain.

Determined, might be inconsistent, but may have (or a many Sal'as

$X_1 + X_2 = 1$ $2x_1 + 2x_2 = 3$	x ₁ +× ₂ =1 x ₁ +2x ₂ =3	$\frac{x_1 + x_2 = 1}{2x_1 + 2x_2 = 2}$
0)	D mar

(c) Suppose that you have a system of equations with fewer equations than unknowns. Might it have zero, one, or infinitely many solutions? Explain.

Undertermined

won't have exactly are sol'n but may have