

Math 300: Quiz the Fourth

This exam is closed book and closed notes. You may not use a calculator. You have until 5 minutes before the hour to finish the in-class portion. The take-home portion is due Monday at the beginning of class.

- 1. True or False. Give a brief justification in each case.
 - (a) Any plane in \mathbb{R}^3 is a subspace of \mathbb{R}^3 .

False - plane must go through the origin

(b) The set of all continuous real-valued functions is a vector space.

True -> one for examples

(c) A vector space can have more than one zero vector.

False -> zeco rectoris orique

(d) A linear transformation is one-to-one if its kernel is empty.

False > Kernel always has o. -> so the premise is always false

(e) Every vector space with more than one vector has more than one subspace.

True. { 33 and V are subspaces of V.

2. Use Cramer's Rule to solve $A\mathbf{x} = \mathbf{b}$, where

$$A = \left[\begin{array}{rrr} 2 & 1 & 5 \\ 2 & -3 & 1 \\ 3 & 1 & 2 \end{array} \right]$$

and
$$b = \begin{bmatrix} 0 \\ 0 \\ 5 \end{bmatrix}$$

$$det A = 2(-6-1) - 1(4-3) + 5(2-(-9))$$

$$= -14 - 1 + 55 = 40$$

$$A(f) = \begin{bmatrix} 0 & 1 & 5 \\ 0 & -3 & 1 \\ 5 & 1 & 2 \end{bmatrix} \rightarrow \det = 5(1+15) = 80 \qquad \chi_1 = \frac{80}{40} = 2$$

$$A_2(f) = \begin{bmatrix} 2 & 0 & 5 \\ 2 & 0 & 1 \\ 3 & 5 & 2 \end{bmatrix} \rightarrow \det = -5(2-10) = \frac{440}{40} \qquad \chi_2 = \frac{40}{40} = 1$$

$$A_2(f) = \begin{bmatrix} 2 & 0 & 5 \\ 2 & 0 & 1 \\ 3 & 5 & 2 \end{bmatrix} \rightarrow \det = 5(-6-2) = -40 \qquad \chi_3 = \frac{-40}{40} = -1$$

$$A_3(f) = \begin{bmatrix} 2 & 1 & 0 \\ 2 & -3 & 6 \\ 3 & 1 & 5 \end{bmatrix} \Rightarrow \det = 5(-6-2) = -40 \qquad \chi_3 = \frac{-40}{40} = -1$$

3. For each given vector space V and subset H of V, determine whether H is a subspace of V.

(a)
$$V = \mathbb{R}^3$$
, $H = \left\{ \begin{bmatrix} a \\ 2b \\ 3a - b \end{bmatrix}$; $a, b \in \mathbb{R} \right\}$

So closedurally +, SC mult, has o realor

(b)
$$V = \mathbb{R}^4$$
, $H = \left\{ \begin{bmatrix} a \\ b \\ c \\ b-a-1 \end{bmatrix}$; $a,b,c \in \mathbb{R} \right\}$

No.
$$\begin{bmatrix} a \\ b \\ -a-1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} a=0 \\ b=0 \\ b \end{bmatrix}$$
 bother $b-a-l=-l$

So of H.

(c) $V = \mathbb{P}_3$, H is the set of polynomials whose coefficients sum to 0.

$$\begin{cases} q_{0} + a_{1} \times + q_{2} \times^{2} + q_{3} \times^{3} & | q_{0} + a_{1} + q_{2} + q_{3} = 0 \end{cases}$$

$$\begin{cases} q_{0} + a_{1} \times + q_{2} \times^{2} + q_{3} \times^{3} & | q_{0} + a_{1} + b_{1} + a_{2} + b_{2} + u_{3} + b_{3} = 0 \end{cases}$$

$$\frac{1}{4 + b_{0} + b_{1} \times + b_{2} \times^{2} + b_{3} \times^{3}} \qquad \begin{cases} q_{0} + a_{1} + a_{1} + a_{2} + b_{2} + u_{3} + b_{3} + u_{3} + u$$

4. Consider the matrix

and its row reduced echelon form

$$R = \left[\begin{array}{cccccc} 1 & 3 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

(a) Determine if $\begin{vmatrix} -5 \\ 1 \\ -3 \\ 1 \\ -1 \\ 1 \end{vmatrix}$ is in nul(A).

(b) Give two nonzero vectors that are in col(A) that are not themselves columns of A.

$$C_{1}+C_{3}=\begin{bmatrix}3\\2\\1\end{bmatrix}$$
both in col(A), as is any lin, comb. of vectors.

(Note: Be explicit about your methods on this one!!)

Math 300: Quiz the Fourth-Take Home Key

1. An $n \times n$ matrix A is symmetric if $A = A^T$. Prove that the set of symmetric $n \times n$ matrices is a subspace of the vector space of all $n \times n$ matrices, and find a spanning set for this subspace.

SOLUTION: Let A and B be symmetric matrices. Then $(A+B)^T = A^T + B^T = A + B$, so symmetric matrices are closed under addition. $(\lambda A)^T = \lambda (A^T) = \lambda A$, so symmetric matrices are closed under scalar multiplication. The all zeroes matrix is symmetric, so the symmetric matrices form a subspace of the space of matrices. To form a spanning set for this set, consider the set of matrices M(ij), which is an $n \times n$ matrix with a 1 in the (i,j) position and 0's everywhere else. The subspace of symmetric matrices is spanned by all matrices of the form M(ij) + M(ji) (that is, matching 1's opposite the diagonal and 0's everywhere else), together with those of the form M(ii) (those with a 1 in a diagonal position).

2. Suppose that A is an $n \times n$ matrix. Prove (carefully) that $A^2 = 0$ if and only if the column space of A is a subspace of the null space of A.

SOLUTION: Suppose first that $A^2 = 0$, and let \mathbf{y} be in the column space of A. Then $\mathbf{y} = A\mathbf{x}$ for some x. But then $A\mathbf{y} = A^2\mathbf{x} = 0\mathbf{x} = 0$, so \mathbf{y} is also in the null space of A. That the column space is a subspace of the null space follows immediately from the fact that it is a subspace of \mathbb{R}^n (and so is closed under addition, etc.), we only needed to prove that it was a *subset* of the null space. Suppose instead that the column space is a subspace of the null space. Consider $A^2\mathbf{x}$ for any vector $\mathbf{x} \in \mathbb{R}^n$. $A^2\mathbf{x} = A(A\mathbf{x})$. Let $\mathbf{y} = A\mathbf{x}$. Then \mathbf{y} is in the column space of \mathbf{x} (by definition), thus it is also in the null space of A (by assumption). Thus $A\mathbf{y} = 0$, or $A(A\mathbf{x}) = A^2\mathbf{x} = 0$ for all x in \mathbb{R}^n , so A^2 must be the A0 matrix.

3. Consider the linear transformation $T: \mathbb{P}_3 \to \mathbb{P}_3$ given by T(p(x)) = p(x) + p'(x). Prove that T is one-to-one and onto, and find an inverse transformation for T.

SOLUTION: We calculate for an arbitrary $p(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3$, $T(p(x) = (a_0 + a_1 x + a_2 x^2 + a_3 x^3) + (a_1 + 2a_2 x + 3a_3 x^2) = (a_0 + a_1) + (a_1 + 2a_2)x + (a_2 + 3a_3)x^2 + a_3x^3$.

We first show that T is 1-1. Assume that T(p(x)) = 0. Setting coefficients equal gives the following homogeneous system.

$$a_0 + a_1 = 0$$

$$a_1 + 2a_2 = 0$$

$$a_2 + 3a_3 = 0$$

$$a_3 = 0$$

which has only the trivial solution. Thus, T(p(x)) = 0 implies that p(x) = 0, thus T is one-to-one.

To show that T is onto, and in the process, create an inverse transformation for T, we show that the equation $T(p(x)) = c_0 + c_1x + c_2x^2 + c_3x^3$ has a solution for all choices of c_0, c_1, c_2, c_3 . But this is the same as solving the system of equations

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$$a_0 + a_1 = c_0$$

 $a_1 + 2a_2 = c_1$
 $a_2 + 3a_3 = c_2$
 $a_3 = c_3$

which has the unique solution

$$(a_0, a_1, a_2, a_3) = (c_0 - c_1 + 2c_2 - 6c_3, c_1 - 2c_2 + 6c_3, c_2 - 3c_3, c_3)$$

So we have shown the map to be onto and have given a formula for the inverse.

$$T^{-1}(c_0 + c_1 x + c_2 x^2 + c_3 x^3) = (c_0 - c_1 + 2c_2 - 6c_3) + (c_1 - 2c_2 + 6c_3)x + (c_2 - 3c_3)x^2 + c_3 x^3$$