

## Homework for 3.7

1. For practice with trig, 3.7.1-3.7.4, also given below. In each case, write the sum as  $R \cos(\omega t - \delta)$

3.7.1  $3 \cos(2t) + 4 \sin(2t)$

SOLUTION: For each of these, think of  $A \cos(2t) + B \sin(2t)$  as defining a complex number  $A + iB$ . Then  $R$  is the magnitude and  $\delta$  is the angle for  $A + iB$ . In this particular case, we see that  $(A, B)$  is in Quadrant I, so  $\delta$  does not need an extra  $\pi$  added to it:

$$R = \sqrt{9 + 16} = 5 \quad \delta = \tan^{-1}(4/3) \Rightarrow \\ 3 \cos(2t) + 4 \sin(2t) = 5 \cos(2t - \tan^{-1}(4/3))$$

3.7.2  $-\cos(t) + \sqrt{3} \sin(t)$

SOLUTION: Note that in this case,  $(-1, \sqrt{3})$  is in Quadrant II, so add  $\pi$  to  $\delta$ . Also, notice that the angle  $\delta$  is coming from a triangle with side 1, 2,  $\sqrt{3}$  (or 30-60-90). In this case,

$$R = \sqrt{1 + 3} = \sqrt{2} \quad \delta = \tan^{-1}(-\sqrt{3}) = -\pi/3 \\ -\cos(t) + \sqrt{3} \sin(t) = 2 \cos(t - (2\pi/3))$$

3.7.3  $4 \cos(3t) - 2 \sin(3t)$

SOLUTION: In this case,  $(4, -2)$  is coming from Quadrant IV, so no need to add  $\pi$  to  $\delta$ . We don't have a special triangle in this case.

$$R = \sqrt{16 + 4} = 2\sqrt{5} \quad \delta = \tan^{-1}(-1/2) \\ 4 \cos(3t) - 2 \sin(3t) = 2\sqrt{5} \cos(t - \tan^{-1}(-1/2))$$

3.7.4  $-2 \cos(\pi t) - 3 \sin(\pi t)$

SOLUTION: In this case  $(-2, -3)$  is in Quadrant III, so we'll need to add  $\pi$  to  $\delta$ .

$$R = \sqrt{4 + 9} = \sqrt{13} \quad \delta = \tan^{-1}\left(\frac{3}{2}\right) + \pi$$

2. Practice with the Model (metric system):

- (a) A spring with a 3-kg mass is held stretched 0.6 meters beyond its natural length by a force of 20 N. If the spring begins at its equilibrium position but a push gives it an initial velocity of 1.2 m/s, find the position of the mass after  $t$  seconds (assume no damping).

SOLUTION:  $m = 3$ ,  $\gamma = 0$ , so we just need the spring constant  $k$ . By Hooke's Law, the force is proportional to the length stretched:

$$k(0.6) = 20 \quad \Rightarrow \quad k = \frac{100}{3}$$

Now we have the IVP:

$$3u'' + \frac{100}{3}u = 0 \quad u(0) = 0, \quad u'(0) = \frac{6}{5}$$

To solve this,

$$3r^2 + \frac{100}{3} = 0 \quad r = \sqrt{\frac{100}{9}}i = \frac{10}{3}i$$

The general solution is

$$C_1 \cos\left(\frac{10}{3}t\right) + C_2 \sin\left(\frac{10}{3}t\right)$$

Putting in the initial conditions,

- (b) A spring with a 4-kg mass has a natural length of 1 meter, and is maintained stretched to a length of 1.3 m by a force of 24.3 N. If the spring is compressed to a length of 0.8 m and then released with zero velocity, find the position of the mass after  $t$  seconds (assume no damping).

SOLUTION:  $m = 4$ ,  $\gamma = 0$ , and the wording of the question implies that the spring is stretched 0.3 m beyond natural length, giving (convert to fractions)

$$\frac{3k}{10} = \frac{243}{10} \quad \Rightarrow \quad k = 81$$

Therefore, we have (recall that "up" is negative)

$$4u'' + 81u = 0 \quad u(0) = -\frac{4}{5} \quad u'(0) = 0$$

Now solve  $u'' + \frac{81}{4}u = 0$ :

$$u(t) = C_1 \cos\left(\frac{9}{2}t\right) + C_2 \sin\left(\frac{9}{2}t\right)$$

Solving for the constants, you should get  $C_1 = -4/5$ ,  $C_2 = 0$ .

- (c) A spring with a mass of 2 kg has damping constant 14 and a force of 6 N is required to keep the spring stretched 0.5 m beyond its natural length. The spring is then stretched to 1 m beyond its natural length and released. Find the position of the mass at any time  $t$ .

SOLUTION:  $m = 2$ ,  $\gamma = 14$  and for the spring constant, we have:

$$\frac{k}{2} = 6 \quad \Rightarrow \quad k = 12$$

The IVP is:  $2u'' + 14u' + 12u = 0$ , with  $u(0) = 1$  and  $u'(0) = 0$

$$u(t) = -\frac{1}{5}e^{-6t} + \frac{6}{5}e^{-t}$$

- (d) A spring with a mass of 3 kg has a damping constant 30 and spring constant 123. Find the position of mass at time  $t$  if it starts at equilibrium with a velocity of 2 m/s.

SOLUTION:

$$3u'' + 30u' + 123u = 0 \quad u(0) = 0 \quad u'(0) = 2$$

Solving, (divide everything by 3 first) we get  $u(t) = \frac{1}{2}e^{-5t} \sin(4t)$ .

- (e) For the spring model above with a mass of 4 kg, find the damping constant that would produce critical damping.

SOLUTION:

$$4u'' + \gamma u' + 123u = 0$$

For critical damping,  $\gamma^2 - 4(4)(123) = 0$ , so that  $\gamma = 4\sqrt{123}$  (only take the positive root!)

- (f) A mass of 20 grams stretches a spring 5 cm. Suppose tha the mass is attached to a viscous damper with a constant damping constant of 400 dyn-s/cm (note: a dyne is a unit of force using centimeters-grams- seconds for units). If the mass is pulled down an additional 2 cm then released, find the IVP that governs the motion of the mass. (Calculator needed-  $g$  should be taken as 980).

SOLUTION: In this case, the spring is stretched to equilibrium:

$$mg - kL = 0 \quad \Rightarrow \quad (20)(980) - k(5) = 0 \quad \Rightarrow \quad k = 3920$$

Therefore, the DE is:

$$20u'' + 400u' + 3920u = 0 \quad u(0) = 2, \quad u'(0) = 0$$

(Note that we could divide everything by 20 to make it a bit easier).

- (g) Suppose we consider a mass-spring system with no damping (the damping constant is then 0), so that the differential equation expressing the motion of the mass can be modeled as

$$mu'' + ku = 0$$

Find value(s) of  $\beta$  so that  $A \cos(\beta t)$  and  $B \sin(\beta t)$  are each solutions to the homogeneous equation (for arbitrary values of  $A, B$ ).

SOLUTION:  $\beta = \sqrt{\frac{k}{m}}$

### 3. Practice with the model (in pounds, from the text)

- (a) A mass weighing 4 lb stretches a spring 2 in. Suppose that the mass is displaced an additional 6 in the positive direction and released. The mass is in a medium that exerts a viscous resistance of 6 lb when the mass has a velocity of 3 ft/s. Formulate the IVP that governs the motion of the mass. (Hint: All units should be consistent. When working with US units, use pounds, feet and seconds.)

SOLUTION: This is Example 1, Section 3.7. For mass,  $mg = 4$ , so

$$m = \frac{4}{g} = \frac{4}{32} = \frac{1}{8}$$

We assume that the damping force is proportional to the velocity, so what is given translates to:

$$6 = \gamma u' = \gamma(3) \quad \Rightarrow \quad \gamma = 2$$

And the spring constant: Change inches into feet so that units are consistent, and

$$mg - kL = 0 \quad \Rightarrow \quad 4 - k\frac{2}{12} = 0 \quad \Rightarrow \quad k = 24$$

Now we have

$$\frac{1}{8}u'' + 2u' + 24u = 0 \quad u(0) = \frac{1}{2} \quad u'(0) = 0$$

- (b) A mass weighing 2 lb stretches a spring 6 in. If the mass is pulled down an additional 3 in and then released, and if there is no damping, determine the IVP that governs the motion of the mass. (You might re-read the hint for (1))

SOLUTION: (Exercise 5, 3.7)

From what's given,  $mg = 2$  and  $mg - kL = 2 - k/2 = 0$ , so  $m = 2/32 = 1/16$  and  $k = 4$ :

$$\frac{1}{16}u'' + 4u = 0 \quad u(0) = \frac{1}{4} \quad u'(0) = 0$$

- (c) (Repeat of 1(f))

- (d) A mass weighing 8 lbs stretches a spring  $\frac{3}{2}$  in. The mass is attached to a damper with coefficient  $\gamma$ . Find  $\gamma$  so that the spring is *underdamped*, *critically damped*, *overdamped*.

SOLUTION:  $mg = 8$ , so  $m = 8/32 = 1/4$ . Further,

$$8 - \frac{3k}{24} = 0 \quad \Rightarrow \quad k = 64$$

The model is then:

$$\frac{1}{4}u'' + \gamma u' + 64u = 0$$

The discriminant in the quadratic formula is  $\gamma^2 - 4mk = \gamma^2 - 64$ :

- If  $\gamma > 8$ , then OVERDAMPED.
- If  $\gamma = 8$ , then CRITICALLY DAMPED.
- If  $0 \leq \gamma < 8$ , then UNDERDAMPED.