

### Chapter 3, Computing Solutions

From the theory, we know that every initial value problem:

$$ay'' + by' + cy = g(t) \quad y(t_0) = y_0 \quad y'(t_0) = v_0$$

has a solution that can be expressed as:

$$y(t) = c_1 y_1 + c_2 y_2 + y_p$$

where  $y_1, y_2$  form a fundamental set of solutions to the homogeneous equation, and  $y_p(t)$  is the (particular) solution to the nonhomogeneous equation.

We first consider the homogeneous ODE:

#### Solving $ay'' + by' + cy = 0$

Form the associated characteristic equation (built by using  $y = e^{rt}$  as the ansatz):

$$ar^2 + br + c = 0 \quad \Rightarrow \quad r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

so that the solutions depend on the discriminant,  $b^2 - 4ac$  in the following way ( $y_h$  refers to the solution of the homogeneous equation):

- $b^2 - 4ac > 0 \Rightarrow$  two distinct real roots  $r_1, r_2$ . The general solution is:

$$y_h(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}$$

If  $a, b, c > 0$  (as in the Spring-Mass model) we can further say that  $r_1, r_2$  are negative. We would say that this system is OVERDAMPED.

- $b^2 - 4ac = 0 \Rightarrow$  one real root  $r = -b/2a$ . Then the general solution is:

$$y_h(t) = e^{-(b/2a)t} (C_1 + C_2 t)$$

If  $a, b, c > 0$  (as in the Spring-Mass model), the exponential term has a negative exponent. In this case (one real root), the system is CRITICALLY DAMPED.

- $b^2 - 4ac < 0 \Rightarrow$  two complex conjugate solutions,  $r = \lambda \pm i\mu$ . Then the solution is:

$$y_h(t) = e^{\lambda t} (C_1 \cos(\mu t) + C_2 \sin(\mu t))$$

If  $a, b, c > 0$ , then  $\lambda < 0$ . In the case of complex roots, the system is said to be UNDERDAMPED. If  $\lambda = 0$  (this occurs when there is no damping), we get pure periodic motion, with period  $2\pi/\mu$ .

#### Solving $y'' + p(t)y' + q(t)y = 0$

Given  $y_1(t)$ , we can solve for a second linearly independent solution to the homogeneous equation,  $y_2$ , by one of two methods:

- By use of the Wronskian: There are two ways to compute this,
  - $W(y_1, y_2) = Ce^{-\int p(t) dt}$  (This is from Abel's Theorem)
  - $W(y_1, y_2) = y_1 y_2' - y_2 y_1'$

Therefore, these are equal, and  $y_2$  is the unknown:  $y_1 y_2' - y_2 y_1' = Ce^{-\int p(t) dt}$

**Summarized Example:**  $y'' + \frac{2}{t}y' - \frac{2}{t^2} = 0$ , with  $y_1 = t$ .

Abel's Theorem:  $W(y_1, y_2) = Ce^{-2 \ln(t)} = C/t^2$

Wronskian:  $ty_2' - y_2$

These should be the same:  $ty_2' - y_2 = \frac{C}{t^2}$  is a linear first order equation. Solve it and ignore the constant to get that  $y_2 = t^{-2}$ .

- By Variation of Parameters (the method that the text uses in Section 3.5), where  $y_2 = u_2(t)y_1(t)$ . See Example 3, p. 171 for an example.

## Solving for the particular solution.

Our two methods were: Method of Undetermined Coefficients and Variation of Parameters.

- Method of Undetermined Coefficients

This method is motivated by the observation that, a linear operator of the form  $L(y) = ay'' + by' + cy$ , acting on certain classes of functions, returns the same class. In summary, we have Table 3.6.1, reproduced below:

if $g_i(t)$ is:	The ansatz $y_{p_i}$ is:
$P_n(t)$	$t^s(a_0 + a_1t + \dots + a_nt^n)$
$P_n(t)e^{\alpha t}$	$t^s e^{\alpha t}(a_0 + a_1t + \dots + a_nt^n)$
$P_n(t)e^{\alpha t} \sin(\mu t)$ or $\cos(\mu t)$	$t^s e^{\alpha t}((a_0 + a_1t + \dots + a_nt^n) \sin(\mu t) + (b_0 + b_1t + \dots + b_nt^n) \cos(\mu t))$

The  $t^s$  term comes from an analysis of the homogeneous part of the solution. That is, multiply by  $t$  or  $t^2$  so that no term of the ansatz is included as a term of the homogeneous solution.

- Variation of Parameters: Given  $y'' + p(t)y' + q(t)y = g(t)$ , with  $y_1, y_2$  solutions to the homogeneous equation, we write the ansatz for the particular solution as:

$$y_p = u_1 y_1 + u_2 y_2$$

From our analysis, we saw that  $u_1, u_2$  were required to solve:

$$\begin{aligned} u_1' y_1 + u_2' y_2 &= 0 \\ u_1' y_1' + u_2' y_2' &= 0 \end{aligned}$$

From which we get the formulas for  $u_1'$  and  $u_2'$ :

$$u_1' = \frac{-y_2 g}{W(y_1, y_2)} \quad u_2' = \frac{y_1 g}{W(y_1, y_2)}$$