

Review of Linearization in Calculus

In Calculus I, the *linearization* of $y = f(x)$ at a point $(a, f(a))$ was defined to be the tangent line to f at a :

$$L(x) = f(a) + f'(a)(x - a)$$

We are going to do something similar here. It is very difficult to analyze a general non-linear system of differential equations, so we will “linearize” the system at the equilibria, and we know how to analyze linear systems.

In Calculus III, we learn how to linearize $z = f(x, y)$ at a point $(a, b, f(a, b))$ - we get the tangent plane:

$$L(x, y) = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$$

From this, you can guess what we do for $w = f(x, y, z)$ at $(a, b, c, f(a, b, c))$:

$$L(x, y, z) = f(a, b, c) + f_x(a, b, c)(x - a) + f_y(a, b, c)(y - b) + f_z(a, b, c)(z - c)$$

and so on.

Vector Fields and Linearization

Given a vector field $\mathbf{F}(x, y)$, we can also linearize the whole by linearizing each function. For example, if

$$\mathbf{F}(x, y) = \begin{bmatrix} f(x, y) \\ g(x, y) \end{bmatrix}$$

Then the linearization at $x = a, y = b$ is given by:

$$\mathbf{L}(x, y) = \begin{bmatrix} f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b) \\ g(a, b) + g_x(a, b)(x - a) + g_y(a, b)(y - b) \end{bmatrix}$$

This is typically written in matrix-vector form:

$$\mathbf{L}(x, y) = \begin{bmatrix} f_x(a, b) & f_y(a, b) \\ g_x(a, b) & g_y(a, b) \end{bmatrix} \begin{bmatrix} (x - a) \\ (y - b) \end{bmatrix} + \begin{bmatrix} f(a, b) \\ g(a, b) \end{bmatrix}$$

The matrix of first partial derivatives has a special name- It is the **Jacobian** matrix for our vector field- You might have heard of this matrix in Calc III since it comes up in optimization problems.

Homework: Linearization and some review

1. Find all solutions to each system of equations.

$$\begin{array}{lll} \text{(a)} & \begin{array}{l} (2+x)(y-x) = 0 \\ (4-x)(y+x) = 0 \end{array} & \text{(b)} \quad \begin{array}{l} x + x^2 + y^2 = 0 \\ y - xy = 0 \end{array} & \text{(c)} \quad \begin{array}{l} x - x^2 - xy = 0 \\ 3y - xy - 2y^2 = 0 \end{array} \end{array}$$

2. Linearize each function about the given point.

$$\begin{array}{ll} \text{(a)} & f(x) = x^2 + 2x + 1 + \cos(x) \text{ at } x = 0 \\ \text{(b)} & f(x, y) = x - 2y + x^2 + e^{xy} \text{ at } x = 1, y = 0. \\ \text{(c)} & \mathbf{F}(x, y) = \begin{bmatrix} -x + y + 2xy \\ -4x - y + x^2 - y^2 \end{bmatrix} \text{ at } (x = 0, y = 0). \\ \text{(d)} & \mathbf{F}(x, y) = \begin{bmatrix} (1+x)\sin(y) \\ 1-x-\cos(y) \end{bmatrix} \text{ at } (x = 0, y = 0). \end{array}$$