

## Some Motivating Examples: Complementary Slackness

Suppose we're given the following primal (max) tableau:

$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	$rhs$
-3	-5	0	0	0	0
1	0	1	0	0	4
0	2	0	1	0	12
3	2	0	0	1	18

The current feasible solution for the primal is given below (in tabular form):

$$\begin{array}{c|ccc} x_1 & x_2 & s_1 & s_2 & s_3 \\ \hline 0 & 0 & 4 & 12 & 18 \end{array} \Rightarrow \begin{array}{l} \mathcal{B} = \{s_1, s_2, s_3\} \\ \mathbf{c}_B^T = [0, 0, 0] \\ \mathbf{y}^T = \mathbf{c}_B^T B^{-1} \end{array} \Rightarrow \begin{array}{c|ccc} e_1 & e_2 & y_1 & y_2 & y_3 \\ \hline -3 & -5 & 0 & 0 & 0 \end{array}$$

In this case, we see that the primal is feasible, and the corresponding dual is not. You can verify the values of  $e_1, e_2$  by substituting the values of  $y_1, y_2, y_3$  into the dual. Below, we will assume that  $\mathcal{B} = \{s_1, s_2, x_1\}$  so that  $B$  changes as well. The final tableau is given below, with the corresponding values of the dual:

$$\begin{array}{c|ccccc} x_1 & x_2 & s_1 & s_2 & s_3 & rhs \\ \hline 0 & -3 & 0 & 0 & 1 & 18 \\ 0 & -2/3 & 1 & 0 & -1/3 & -2 \\ 0 & 2 & 0 & 1 & 0 & 12 \\ 1 & 2/3 & 0 & 0 & 1/3 & 6 \end{array} \quad \begin{array}{l} \mathcal{B} = \{s_1, s_2, x_1\} \\ \mathbf{c}_B^T = [0, 0, 3] \\ \mathbf{y}^T = \mathbf{c}_B^T B^{-1} = [0, 0, 1]^T \end{array}$$

$$\begin{array}{c|ccc} x_1 & x_2 & s_1 & s_2 & s_3 \\ \hline 6 & 0 & -2 & 12 & 0 \end{array} \quad \begin{array}{c|ccc} e_1 & e_2 & y_1 & y_2 & y_3 \\ \hline 0 & -3 & 0 & 0 & 1 \end{array}$$

On the left, the primal is not feasible, and on the right, the dual is not feasible either. In both cases, the current value of  $z = w = 18$ . We now re-run all of the computations using another basis:  $\mathcal{B} = \{x_1, x_2, s_3\}$ . We start by obtaining the final tableau:

$$\begin{array}{c|ccccc} x_1 & x_2 & s_1 & s_2 & s_3 & rhs \\ \hline 0 & 0 & 3 & 5/2 & 0 & 42 \\ 1 & 0 & 1 & 0 & 0 & 4 \\ 0 & 1 & 0 & 1/2 & 0 & 6 \\ 0 & 0 & -3 & -1 & 1 & -6 \end{array} \quad \begin{array}{l} \mathcal{B} = \{x_1, x_2, s_3\} \\ \mathbf{c}_B^T = [3, 5, 0] \\ \mathbf{y}^T = \mathbf{c}_B^T B^{-1} = [3, 5/2, 0]^T \end{array}$$

Now we have:

$$\begin{array}{c|ccc} x_1 & x_2 & s_1 & s_2 & s_3 \\ \hline 4 & 6 & 0 & 0 & -6 \end{array} \quad \begin{array}{c|ccc} e_1 & e_2 & y_1 & y_2 & y_3 \\ \hline 0 & 0 & 3 & 5/2 & 0 \end{array}$$

This is dual feasible, but primal infeasible.

As the final computation, consider the basis  $\{x_1, x_2, s_1\}$ .

$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	$rhs$
0	0	0	3/2	1	36
1	0	0	-1/3	1/3	2
0	1	0	1/2	0	6
0	0	1	1/3	-1/3	2

$\mathcal{B} = \{x_1, x_2, s_1\}$   
 $\mathbf{c}_B^T = [3, 5, 0]$   
 $\mathbf{y}^T = \mathbf{c}_B^T B^{-1} = [0, 3/2, 1]^T$

Now we have:

$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
2	6	2	0	0

$e_1$	$e_2$	$y_1$	$y_2$	$y_3$
0	0	0	3/2	1

In this case, both the primal and dual are feasible, so this is the optimal solution for both.

*Did you notice* where the zeros appear? If you were to dot the solution to the primal with the solution to the dual, you **always get zero**. This is what is meant by “complementary slackness”.